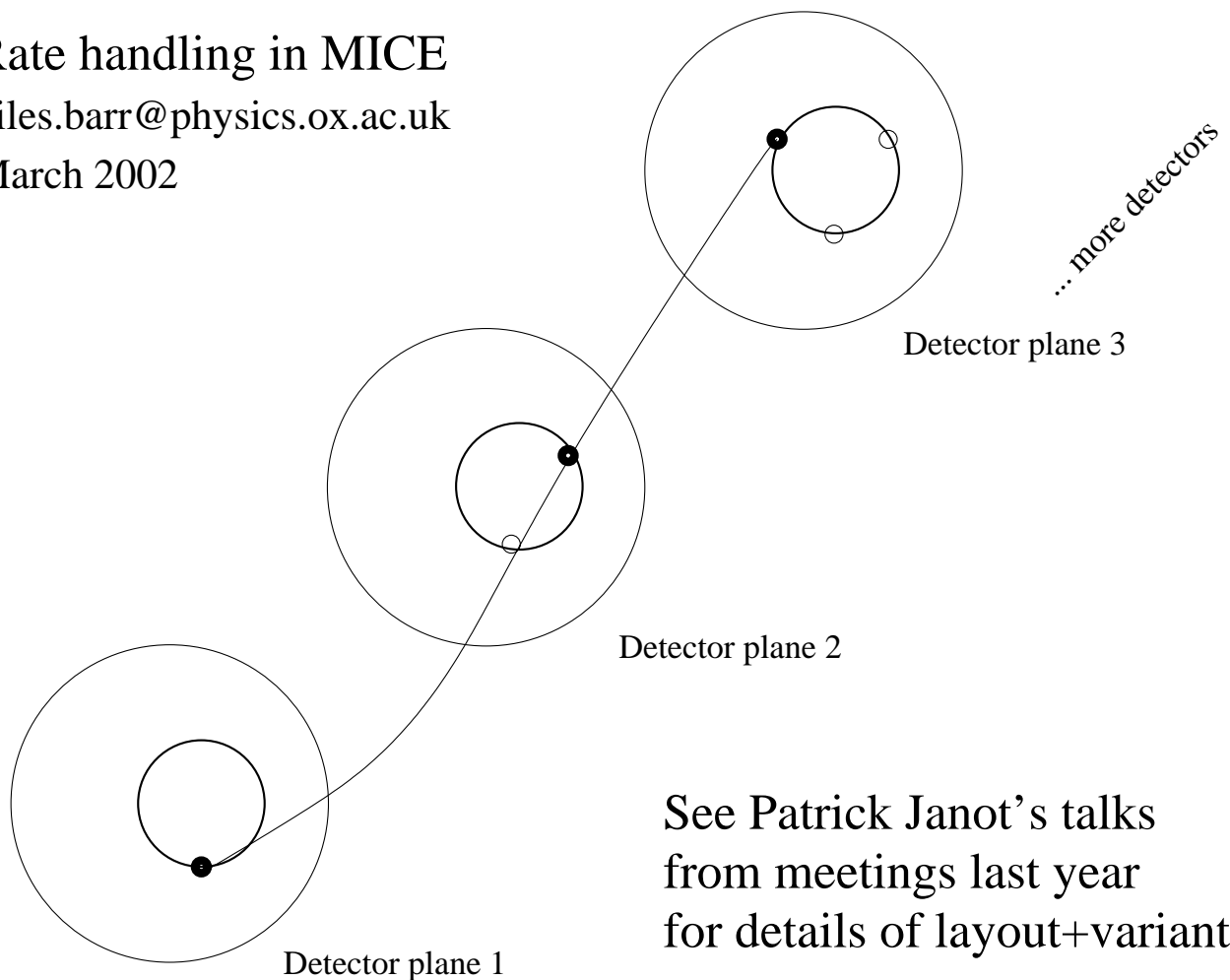


# Rate handling in MICE

giles.barr@physics.ox.ac.uk

March 2002



See Patrick Janot's talks  
from meetings last year  
for details of layout+variants.

Three detectors gives six measured quantities (x,y in each).

- Four of these give measurements we want:

(x,y) of centre of circle

radius of circle

starting point on circle (relative size of px and py)

- Two more can be used for constraints

To be conservative, I say that the radius of the circle in the third detector is used as a cross check and the position around the circle can be used to throw out wrong combinations.

Figure 1: slide 1

(This complication was motivated by somehow thinking that background from straight tracks is more nasty than curly ones).

Now, the probability that three random points satisfy this criterion is:

$$P3 = md/c = 4 \times 0.5 / 500 = 0.4\%$$

$c$  = circumference of circle  
 $m$  = 'roadwidth' for finding track in units of pixels/fibres  
 $d$  = size of each pixel

If we add another detector, we get two more constraints we can use to eliminate fake combinations of points. Generalising to  $N$  detectors,

$$PN = (md/c)^{N-2} (md \ 2\pi / c)^{N-3}$$

Now calculate some numbers. Let

$a$  = #hits in \*EACH\* detector within time window

	N=3	N=4	N=5
PN	4 e -3	4 e -7	1 e -10
a= 2	0.032	6 e -6	1 e -9
a = 10	4	4 e -3	4 e -7
a = 100	4000	40	0.4

(This is with  $c = 500\text{mm}$  ( $r = 15\text{cm}$ ),  $d = 0.5\text{mm}$ ,  $m = 4$ )

That was all where ‘hit’ meant spacepoints. OK for pixels, but for fibres (or other projective detector), we have to combine hits on each fibre to make spacepoints.

[\*Discussion omitted\*]

f = fraction of detector area within ‘roadwidth’

3 planes, no inefficiencies	$p_3 = f a^3 + a(1-f)$
3 planes, one inefficiency	$q_3 = 3 a^2 - 2 a$
4 planes, no inefficiencies	$p_4 = f^2 a^4 + a(1-f^2)$
4 planes, one inefficient plane	$q_4 = 4 f a^3 + a(1-4f)$

... Slightly more sophistication...

... Plots combining these probabilities to make spacepoints from hits with the probabilities to make tracks from spacepoints (as on previous slide).

## Conclusions

- \* Calculations of combinations of spacepoints to tracks and (for fibres) hits to spacepoints.
- \* No matter what happens, we are dead very quickly as the rate goes up.
- \* We are discussing the difference of whether a=3 is the limit or a=5, but not a=10. Therefore, we cannot beat a high rate with the detectors – the rate must not be there in the first place.
- \* a depends on the time window and the road width – these should be made small if we fear a high rate.

# Comparison of SciFi configurations – one inefficiency

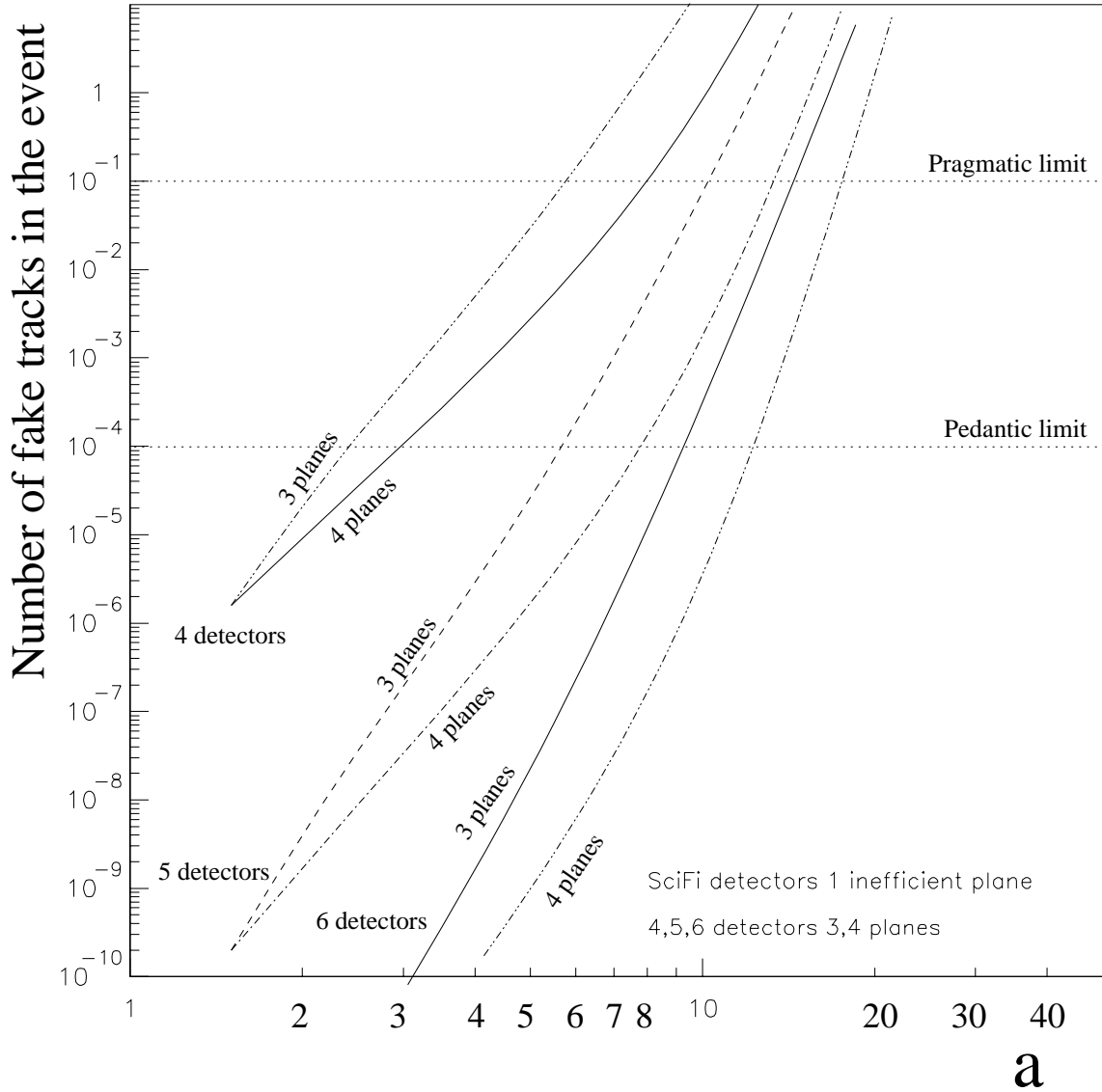


Figure 4:

# Comparison of SciFi configurations – no inefficiency

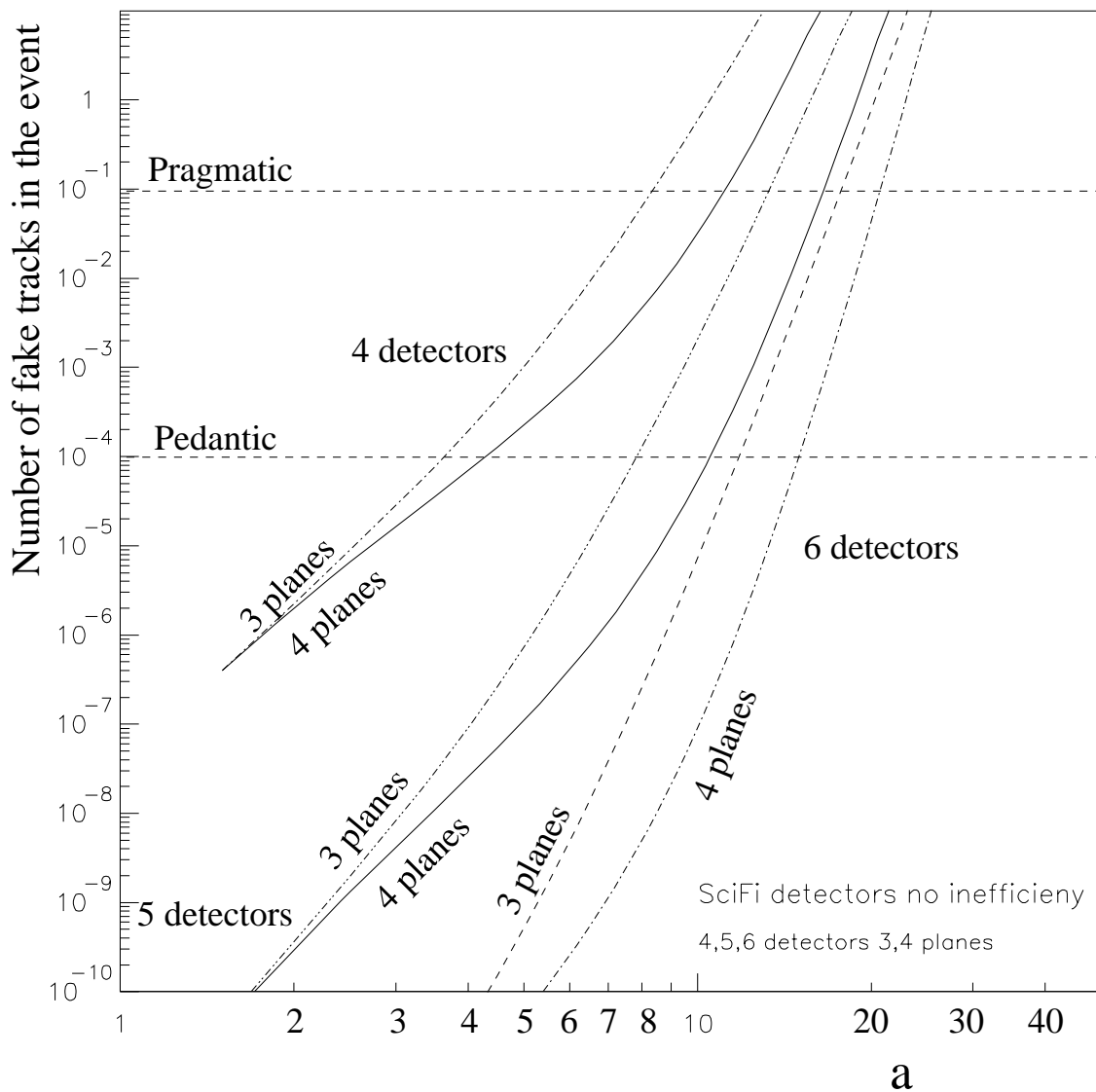
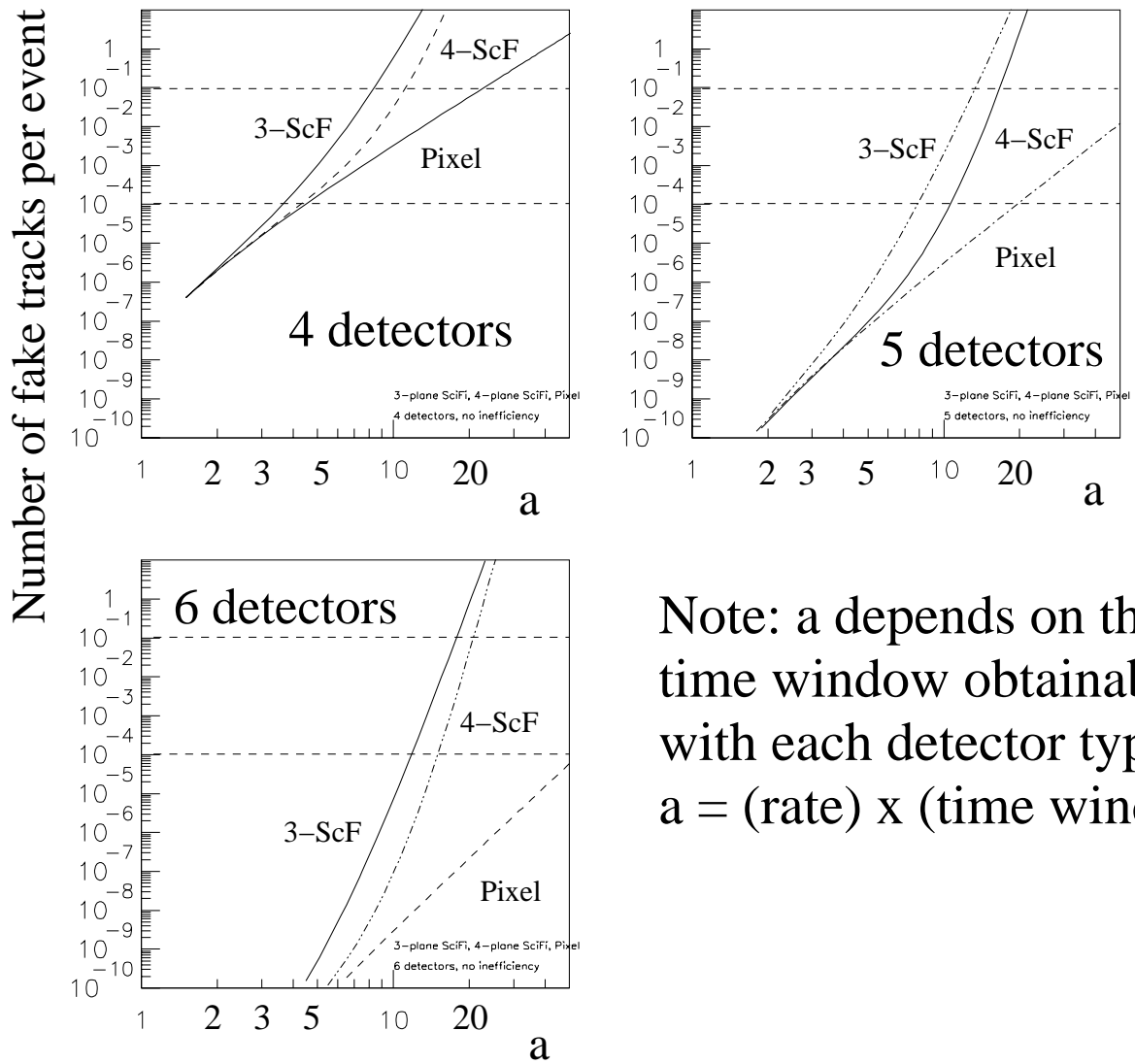


Figure 5:

Compare detector types with same number of detectors of each type.



Note: a depends on the time window obtainable with each detector type.  
 $a = (\text{rate}) \times (\text{time window})$

Figure 6:

## Compare effect of allowing an inefficient Sci-Fi plane or an inefficient Pixel detector

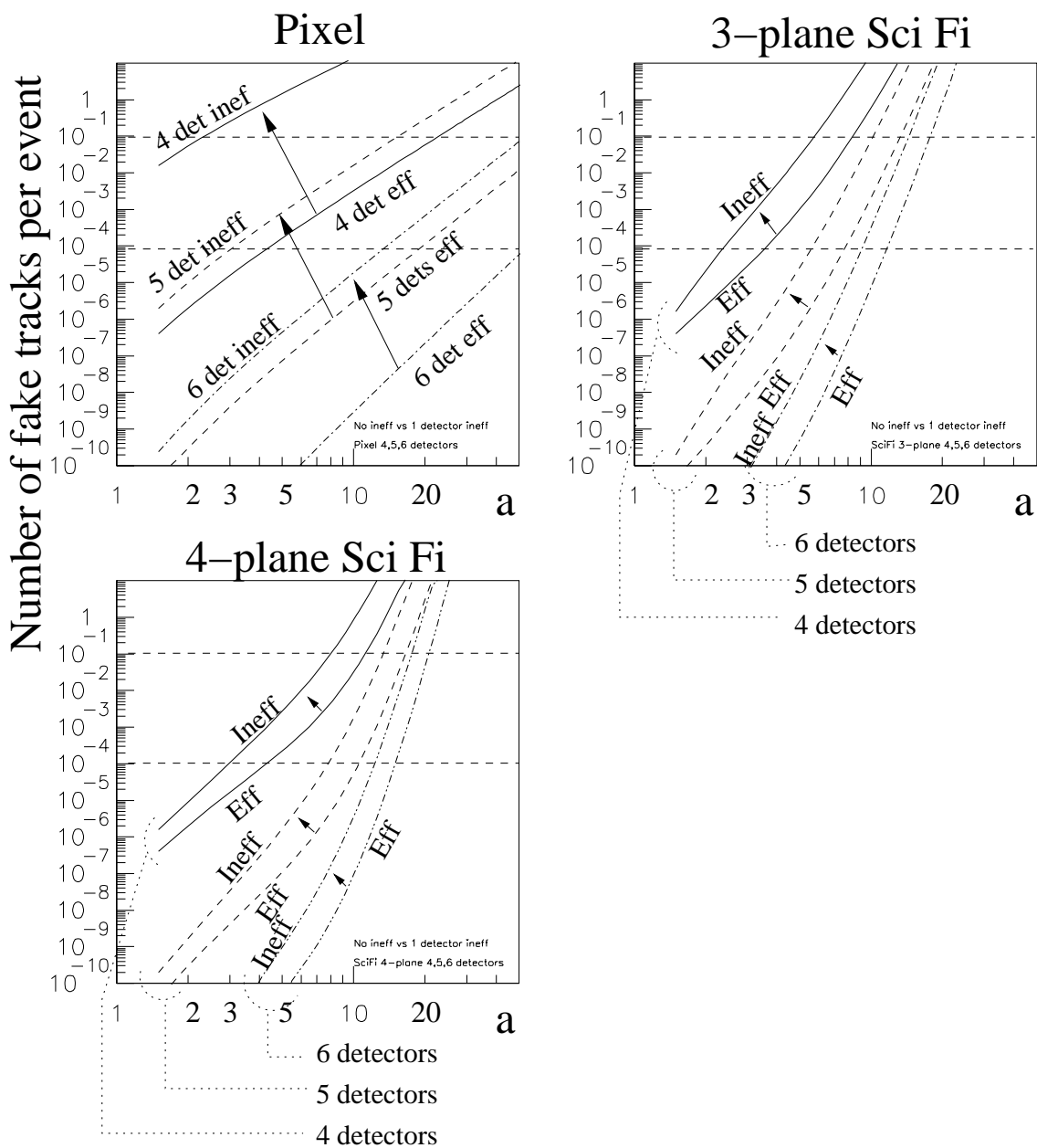


Figure 7: